

# Visualization By Example

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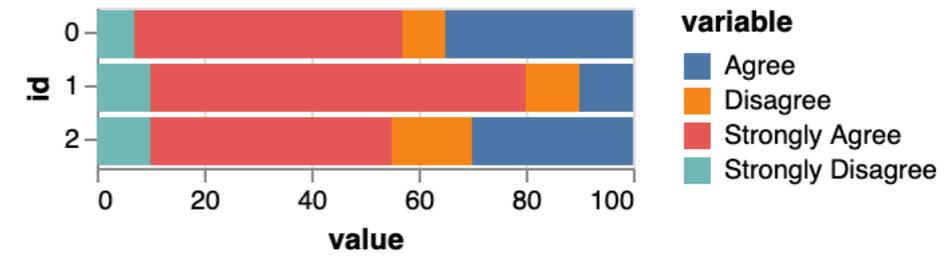
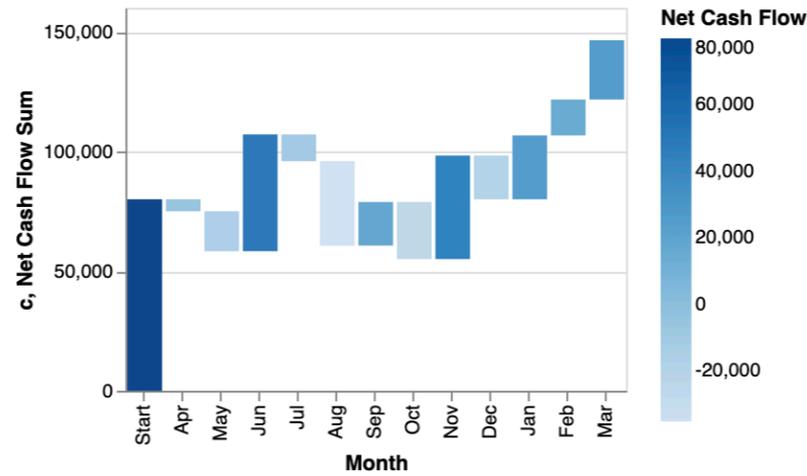
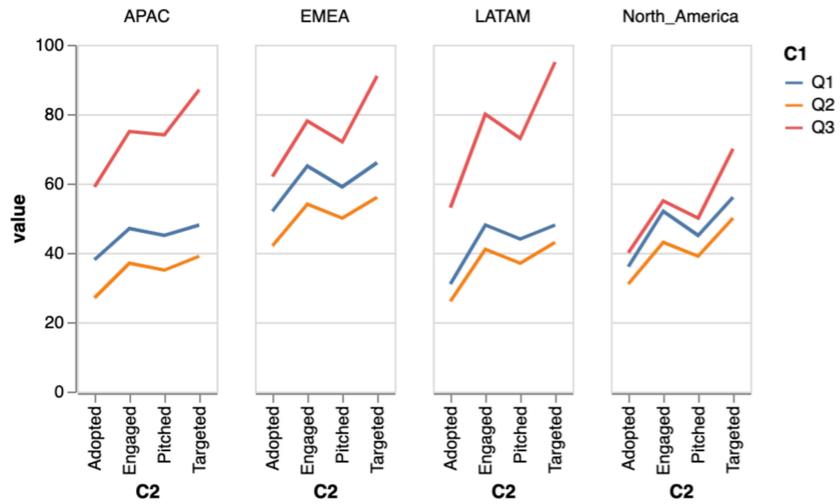
<sup>4</sup>University of Texas, Austin



*Read the paper!*



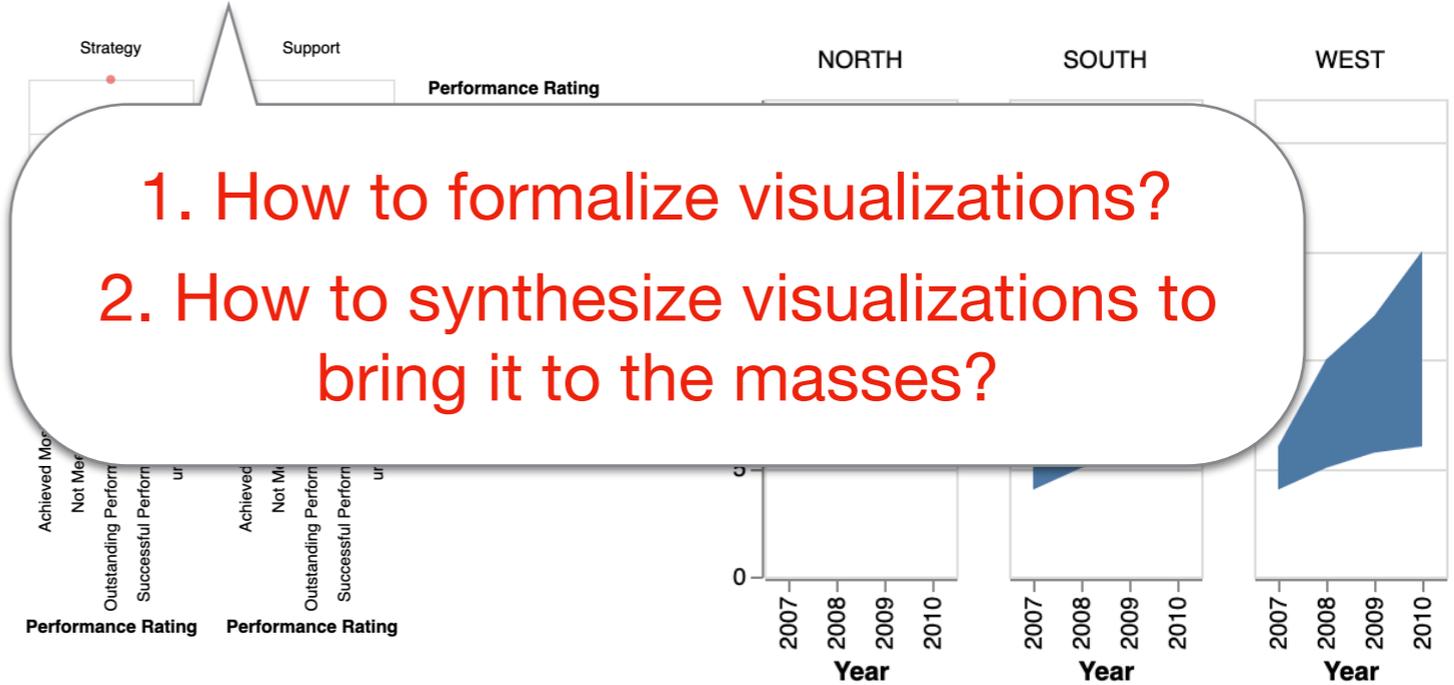
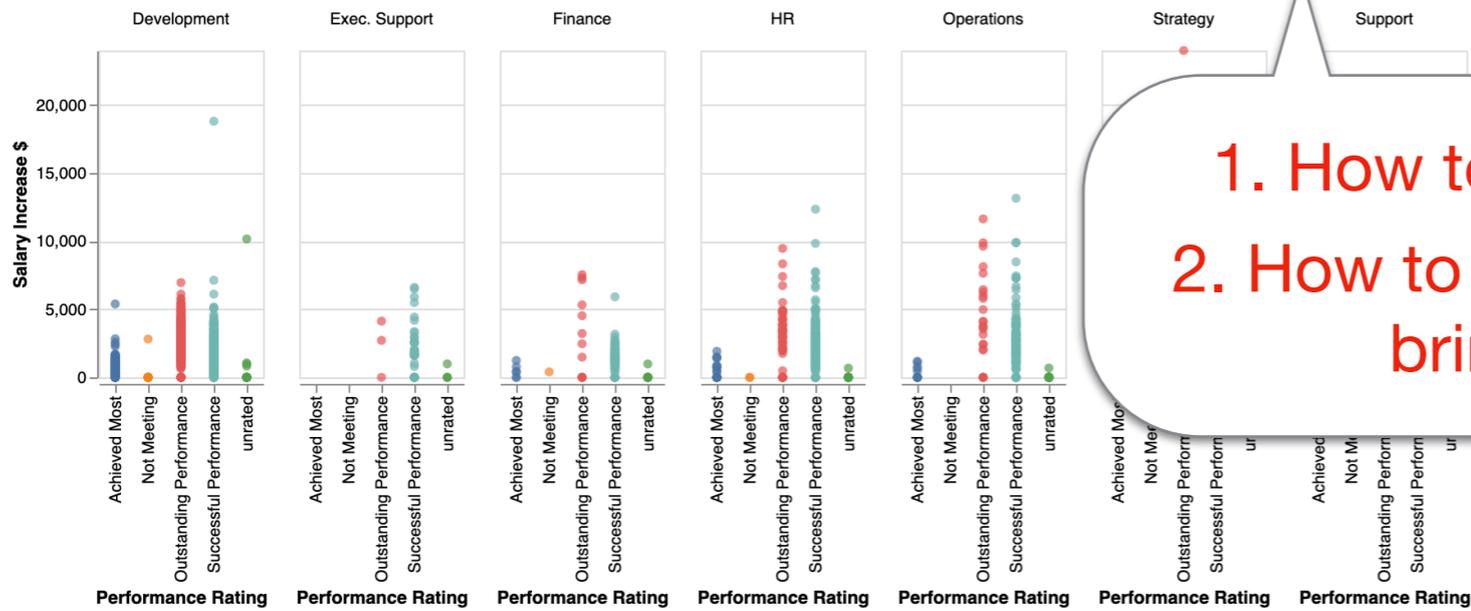
# Visualizations



Product price in different region

Net cash flow in a year

Survey result



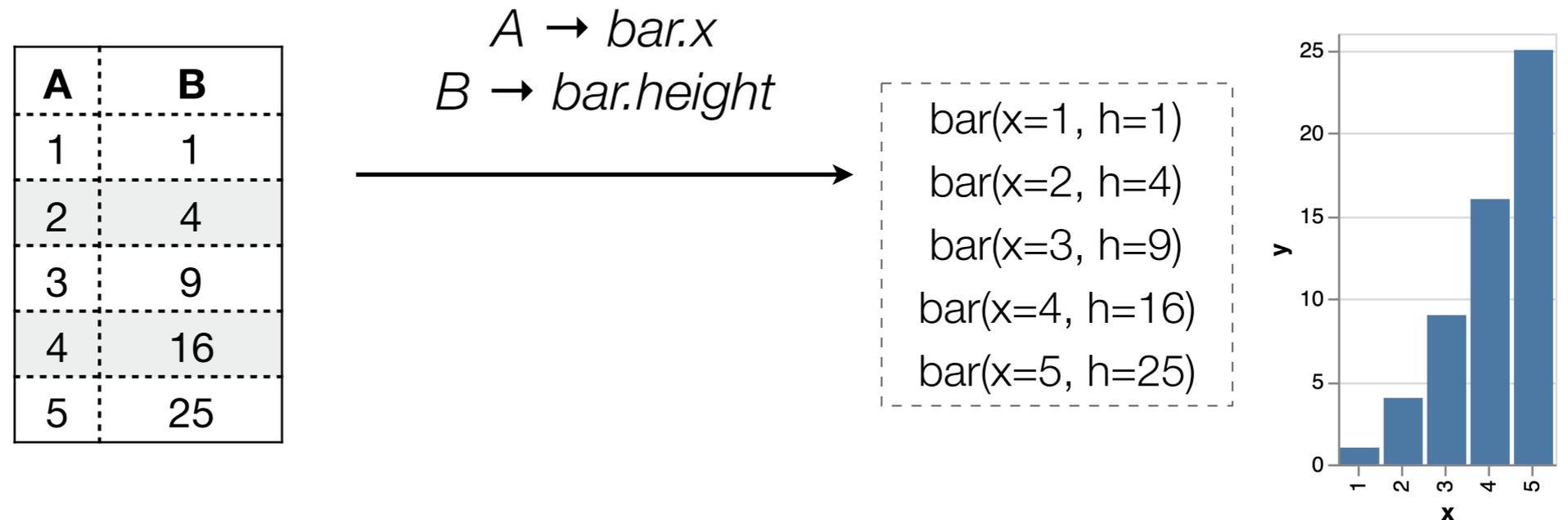
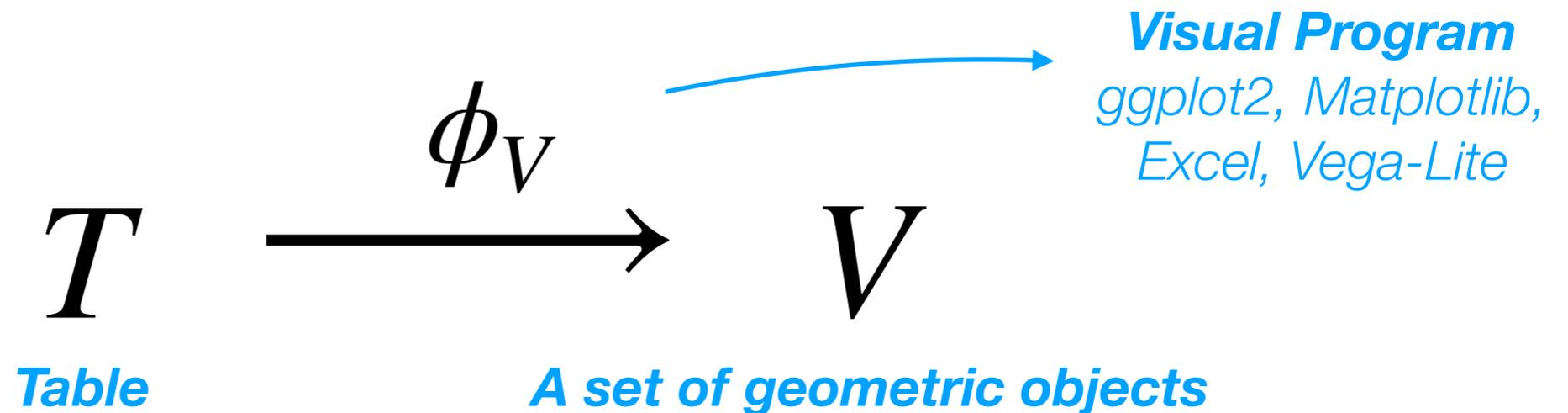
Performance rating distribution for each department

Housing price in different region

# Formalizing Visualizations

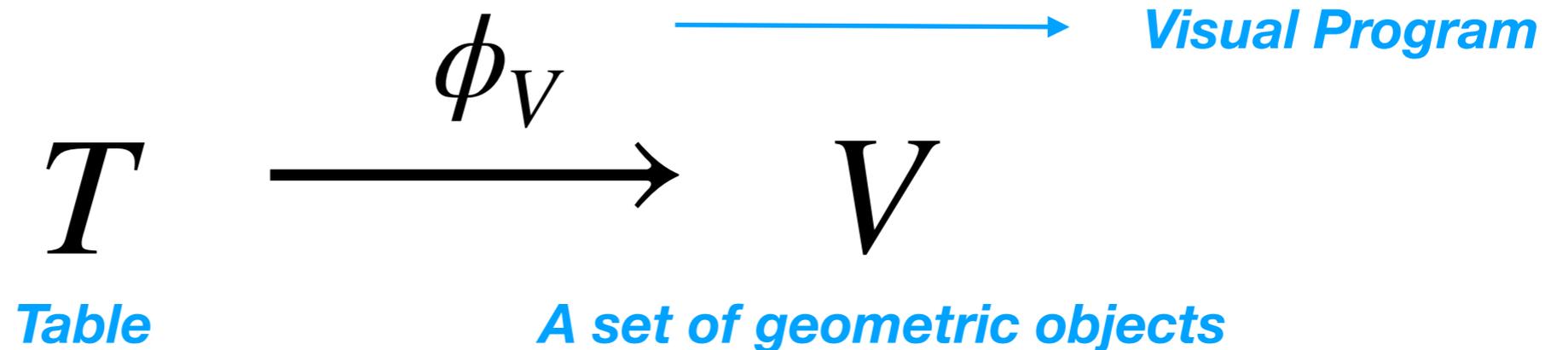
“Transformation of the symbolic into the geometric”

[McCormick et al. 1987]



# Visualization in Practice

Visual program alone is often insufficient.

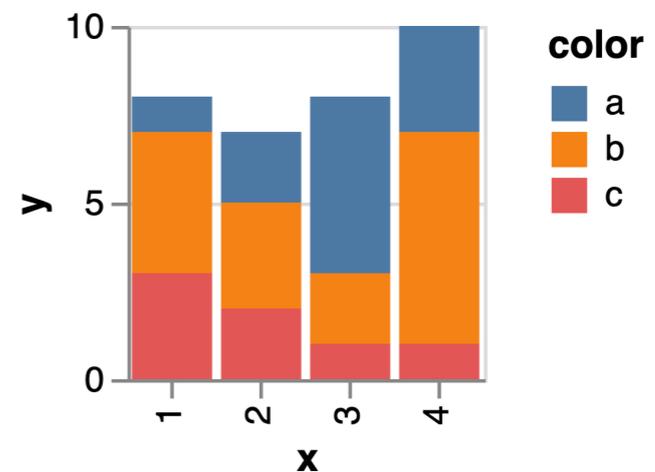


X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

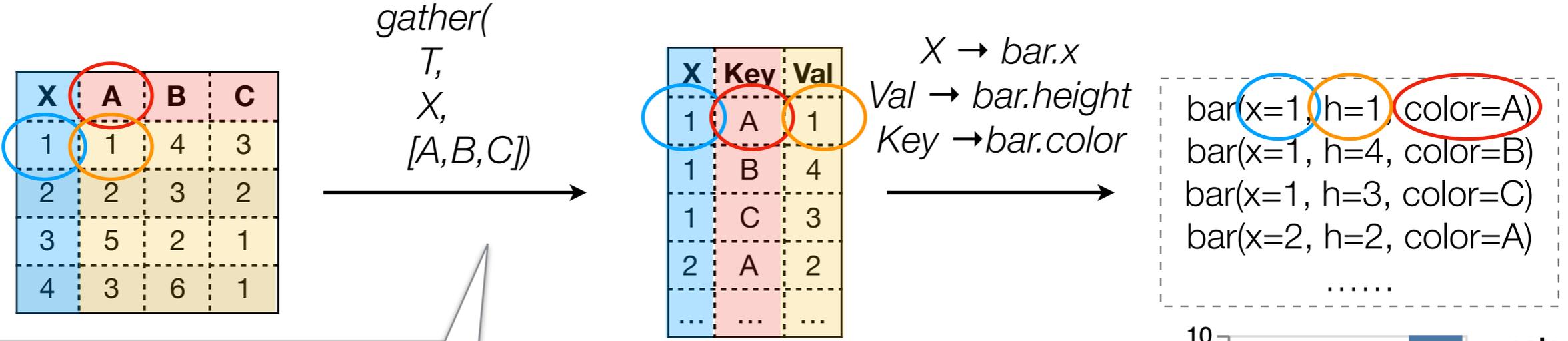
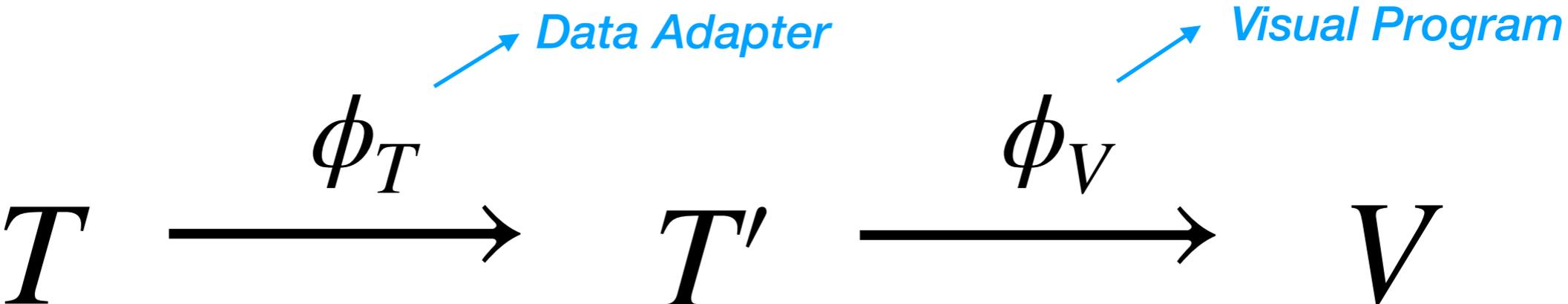
?

bar(x=1, h=1, color=A)  
bar(x=1, h=4, color=B)  
bar(x=1, h=3, color=C)  
bar(x=2, h=2, color=A)  
.....

$\phi_V$  expects a certain shape of the input table  
Expects 3 columns that map to bar.x, bar.height, bar.color



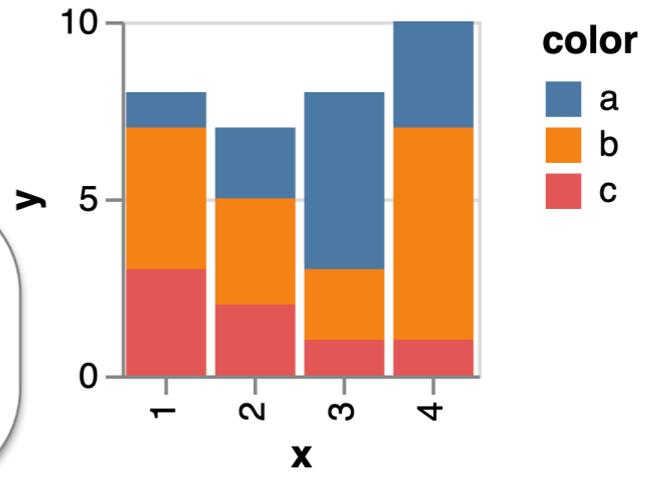
# Visualization in Practice



Gather

(1) turn **A,B,C** into the **Key** column  
 (2) move values in **A,B,C** columns into the **Val** column

**Data adapter prepares the input table to match the shape expected by  $\phi_V$**



# Visualization Challenges

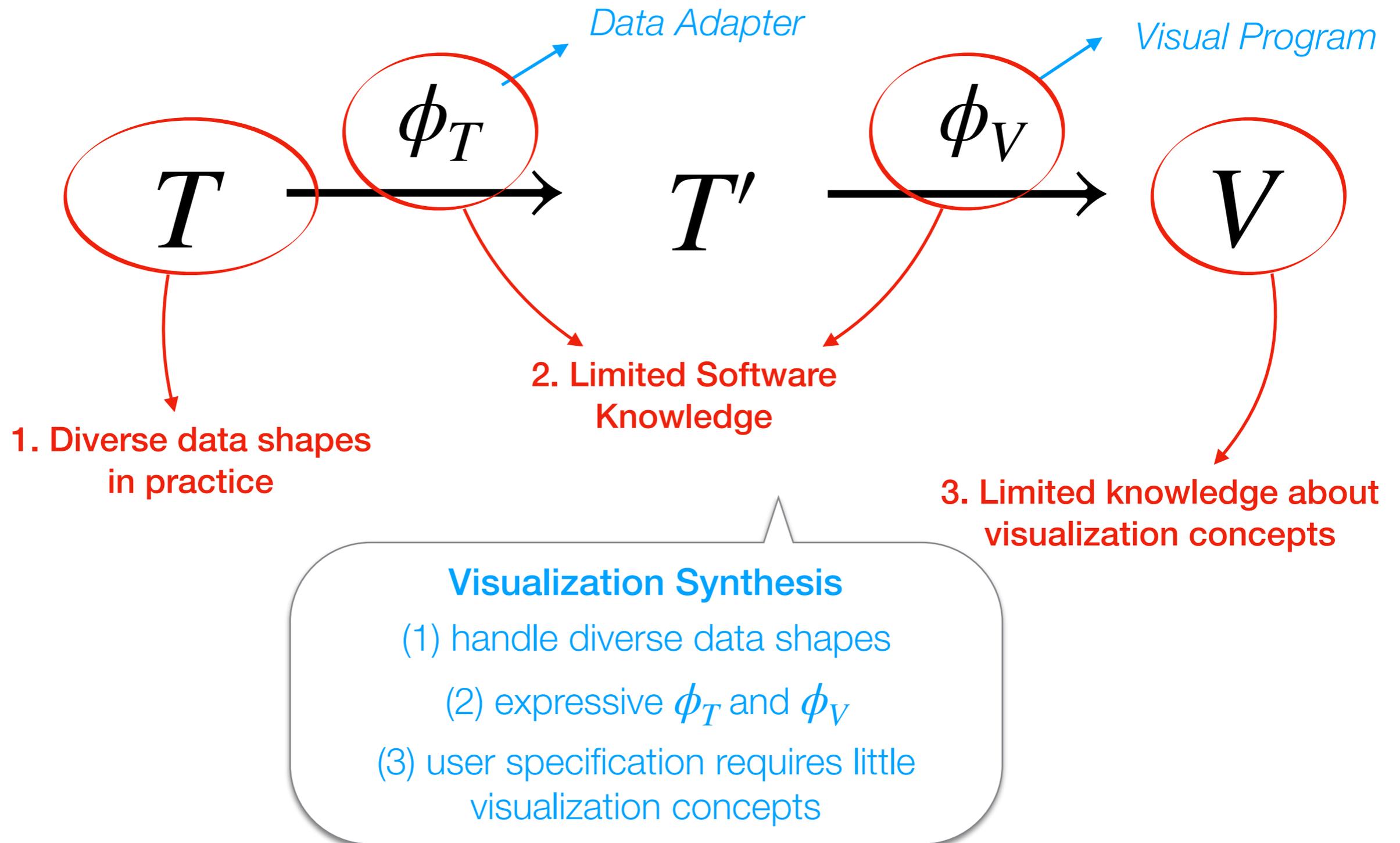
1. Users need to master *both* data prep libraries and visualization libraries.



2. Reshaping and aggregation of data requires deep data transformation insight. [Feng et al. 2018]

3. Change of visualization designs requires frequent change of data adapters.

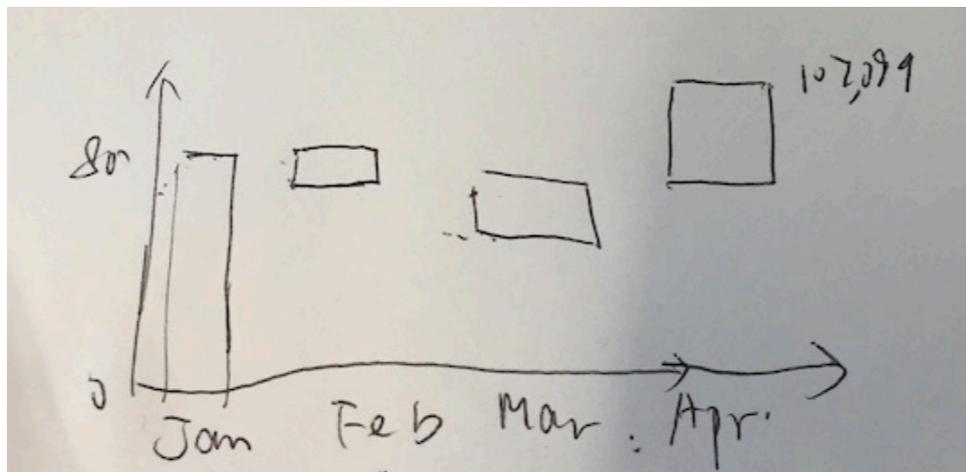
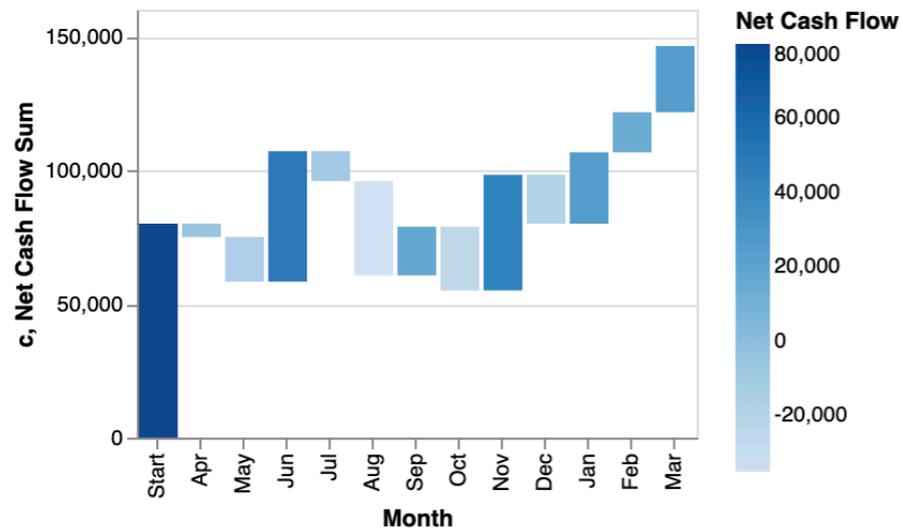
# Visualization Challenges [Gatto 2015]



Gatto, Malu AC. "Making research useful: Current challenges and good practices in data visualization." (2015).

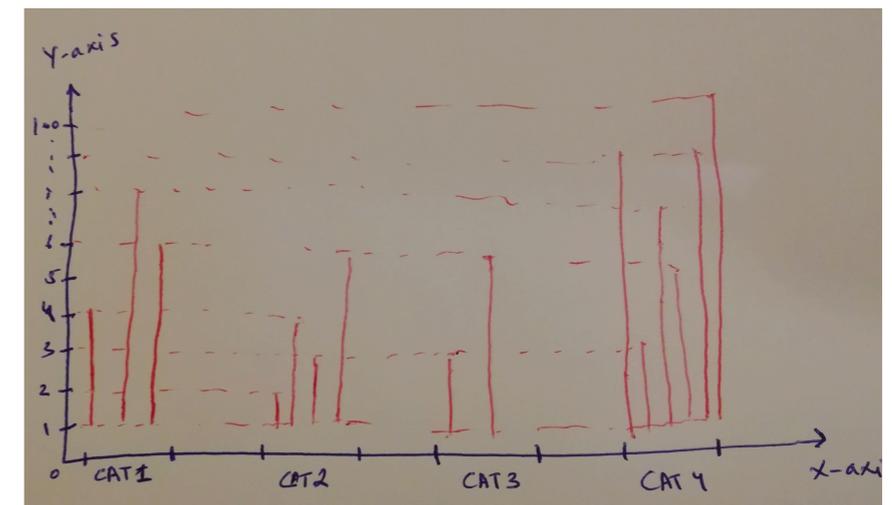
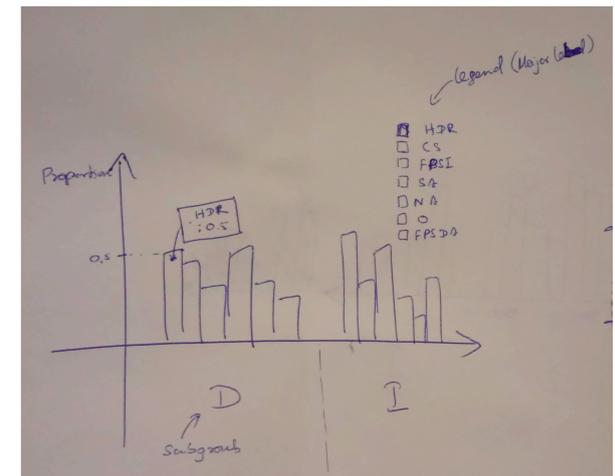
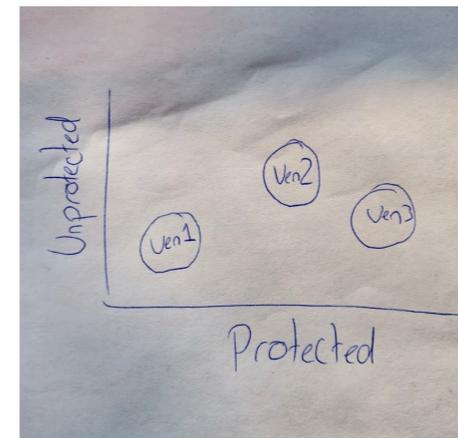
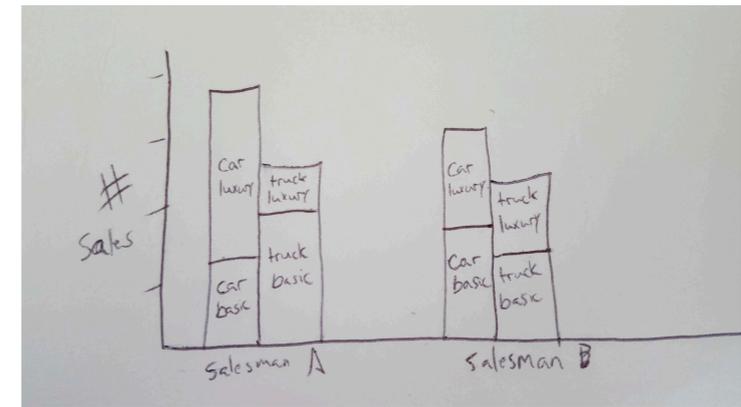
# How to specify visualization?

How would you explain intent of this visualization?

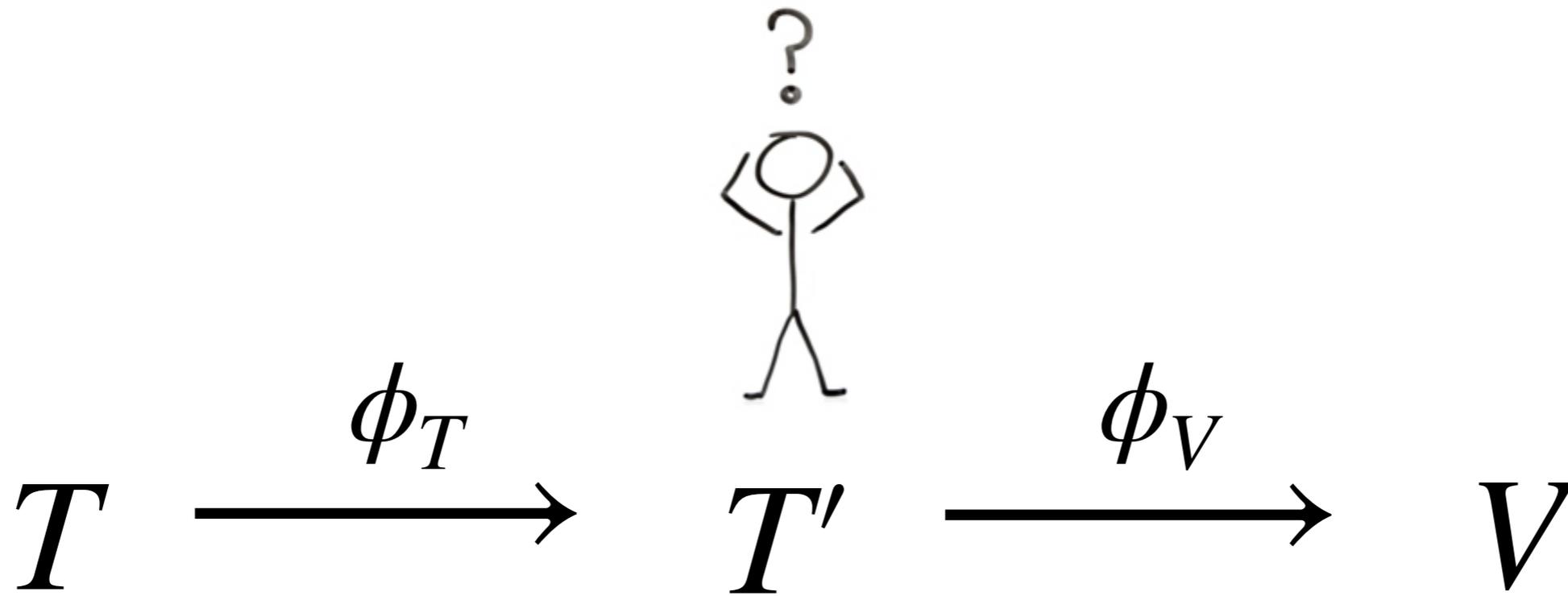


## Partial visualization

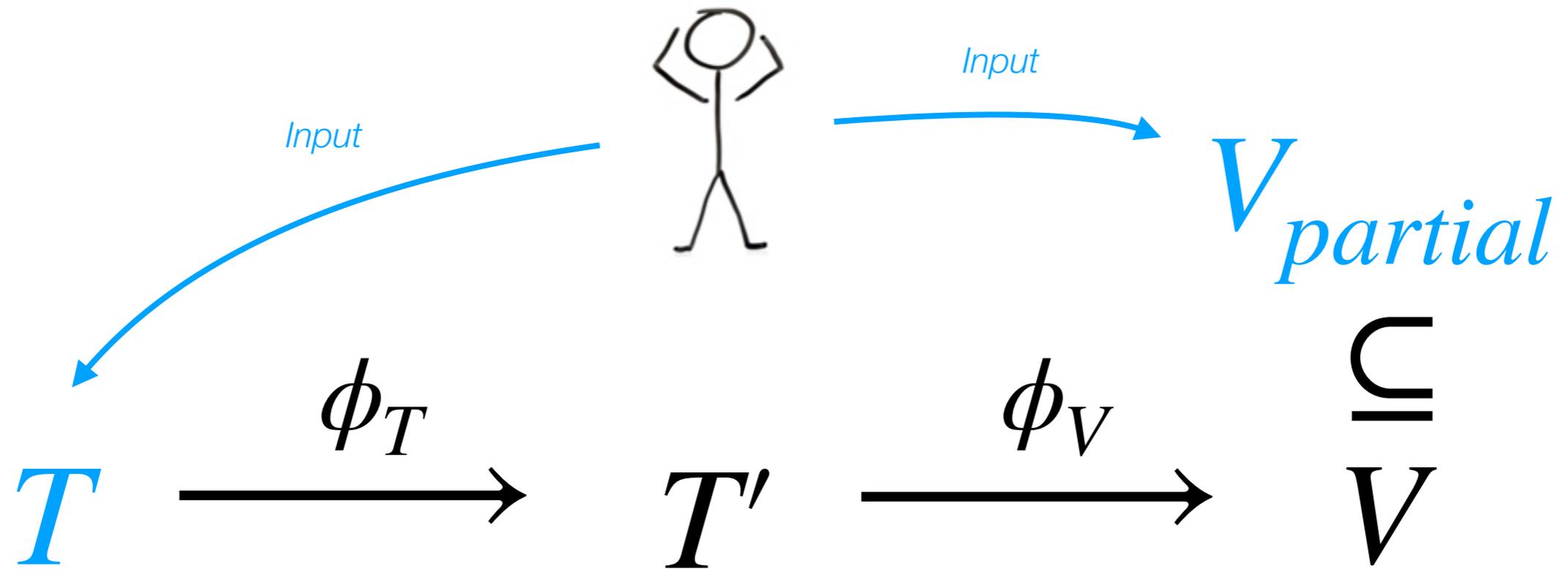
A subset of geometric objects of the final visualization



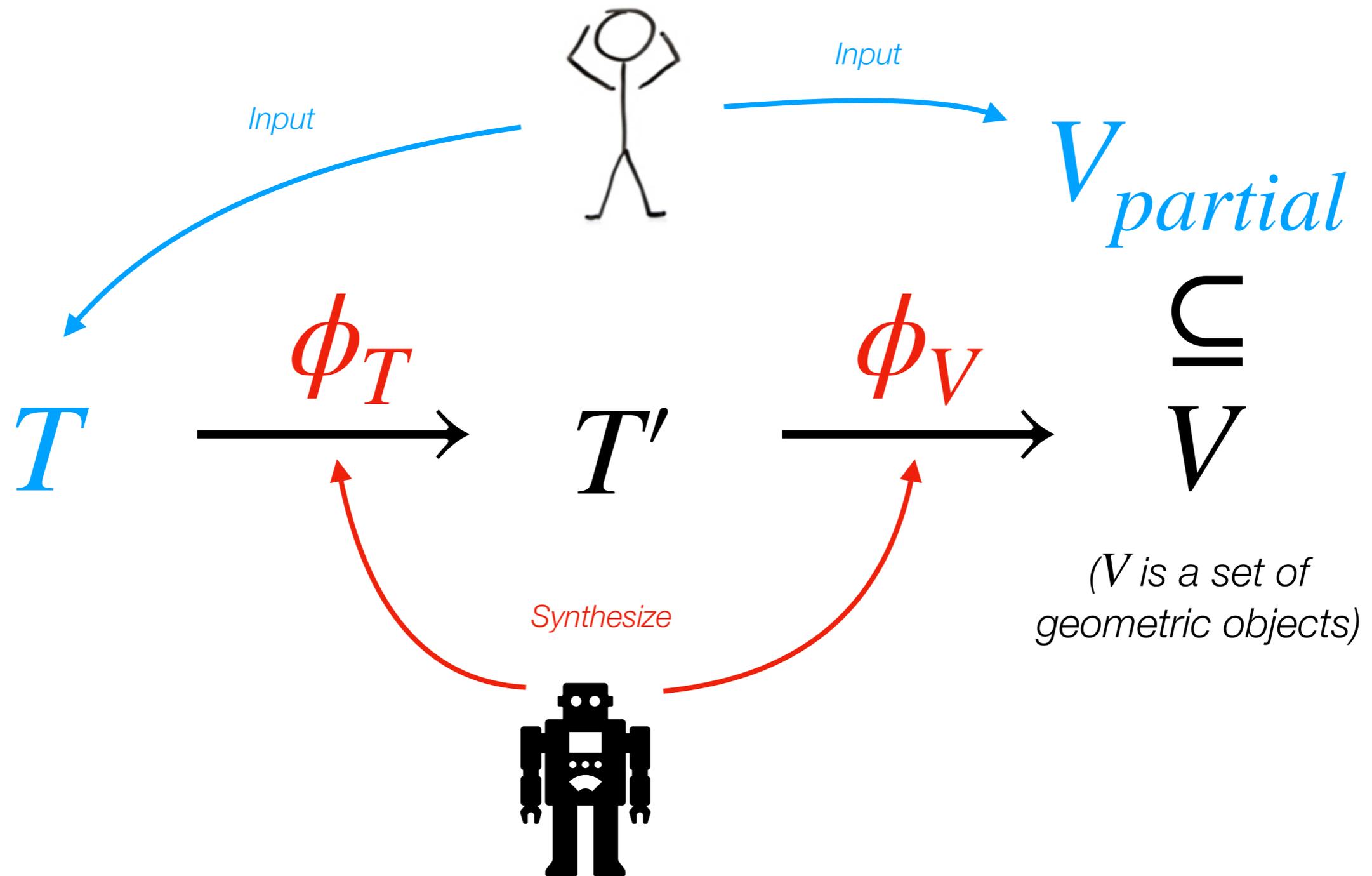
# Visualization by Example



# Visualization by Example



# Visualization by Example

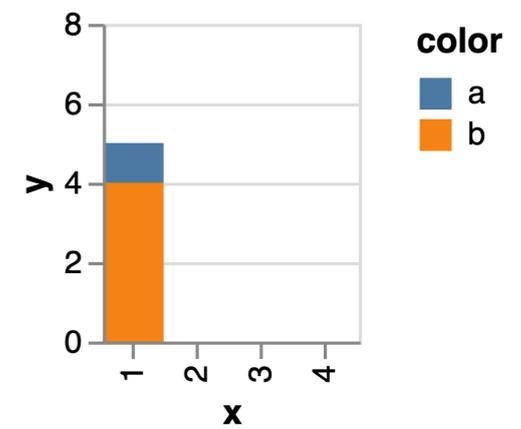


Given  $T$ ,  $V_{partial}$ , synthesize  $\phi_T, \phi_V$ , such that  $\phi_V(\phi_T(T)) \supseteq V_{partial}$

# Visualization by Example

**3. Weak Specification:**  
 “ $\subseteq$ ” instead of “=”

**2. Potentially large input table**  
 e.g. 3000 x 10

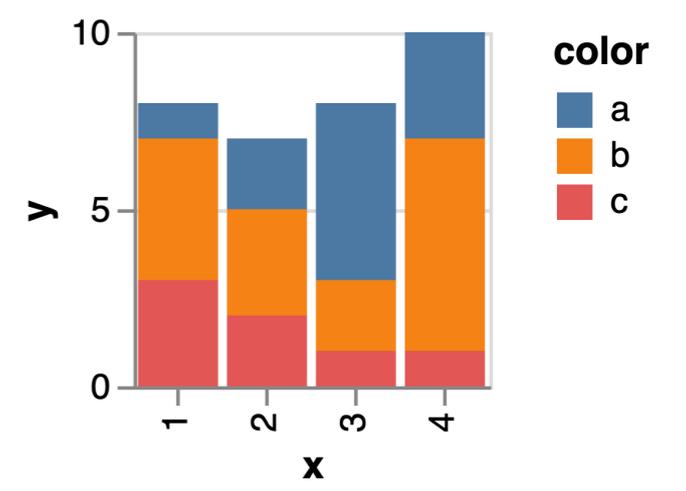


$V_{partial}$

bar(x=1, h=1, color=A)  
 bar(x=1, h=4, color=B)

$\cup$

bar(x=1, h=1, color=A)  
 bar(x=1, h=4, color=B)  
 bar(x=1, h=3, color=C)  
 bar(x=2, h=2, color=A)  
 .....



$T$

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

$\phi_T$

gather(  
 $T$ ,  
 $id=X$ ,  
 $key=[A,B,C]$ )

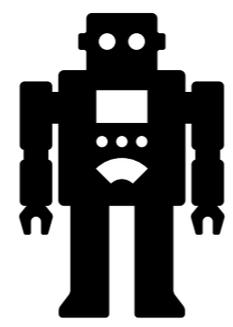
X	Key	Val
1	A	1
1	B	4
1	C	3
2	A	2
...	...	...

$\phi_V$

$X \rightarrow bar.x$   
 $Val \rightarrow bar.height$   
 $Key \rightarrow bar.color$

**1. Compositional Synthesis:**  
 $\phi_T \in \mathcal{L}_T$  and  $\phi_V \in \mathcal{L}_V$

Requirement:  
 $\phi_V(\phi_T(T)) \supseteq V_{partial}$



# Visualization synthesis

$T$

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

$\phi_T$



$T'$

$\phi_V$



$\subseteq$

$V$

$V_{partial}$

bar(x=1, h=1, color=A)  
bar(x=1, h=4, color=B)

Requirement:

$$\phi_V(\phi_T(T)) \supseteq V_{partial}$$

# Visualization synthesis

Step 1: decompile visualization

s.t.,  $\phi_V(T_{sketch}) = V_{partial}$

$T$

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1



$T_{sketch}$

X	Key	Val
1	A	1
1	B	4

$\subseteq$

$T'$



$\phi_V$

$X \rightarrow bar.x$   
 $Val \rightarrow bar.height$   
 $Key \rightarrow bar.color$



$V_{partial}$

$bar(x=1, h=1, color=A)$   
 $bar(x=1, h=4, color=B)$

$\subseteq$

$V$

Requirement:

$\phi_V(\phi_T(T)) \supseteq V_{partial}$

# Visualization synthesis

Step 1: decompile visualization

$$\text{s.t., } \phi_V(T_{sketch}) = V_{partial}$$

Step 2: Synthesize data adapter

$$\text{s.t., } T_{sketch} \subseteq \phi_T(T)$$

$T$

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

$\phi_T$   
gather(  
 $T$ ,  
 $id=X$ ,  
 $key=[A,B,C]$ )

$T_{sketch}$

X	Key	Val
1	A	1
1	B	4

$\subseteq$

$T'$

$\phi_V$   
 $X \rightarrow bar.x$   
 $Val \rightarrow bar.height$   
 $Key \rightarrow bar.color$

$V_{partial}$

bar(x=1, h=1, color=A)  
bar(x=1, h=4, color=B)

$\subseteq$

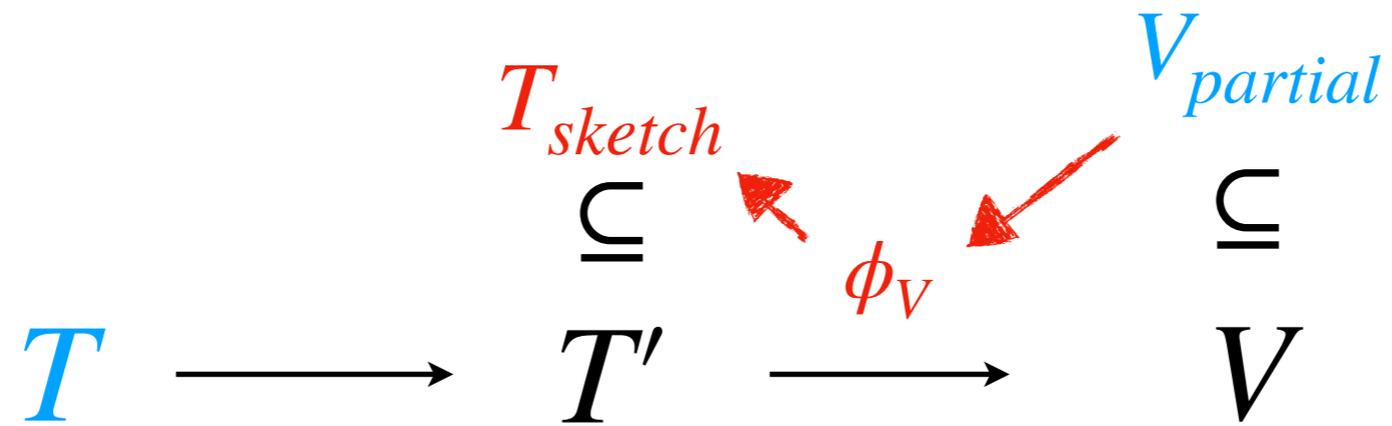
$V$

Key: push the containment requirement from visualization to data adapter.

Requirement:

$$\phi_V(\phi_T(T)) \supseteq V_{partial}$$

# Step 1: Decompile Visualization

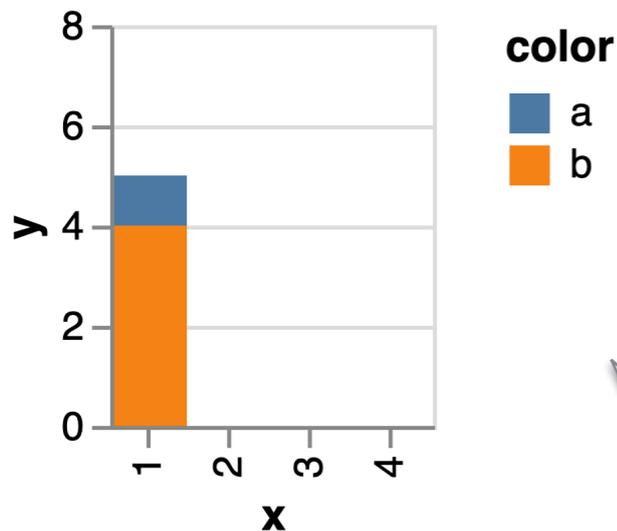


Requirement:  
 $\phi_V(T_{sketch}) = V_{partial}$

What data generates  $V_{partial}$ ?

What mapping generates  $V_{partial}$ ?

bar(x=1, h=1, color=A)  
 bar(x=1, h=4, color=B)



$\phi_V$   
 $C1 \rightarrow bar.x$   
 $C2 \rightarrow bar.height$   
 $C3 \rightarrow bar.color$

(other alternatives ...)

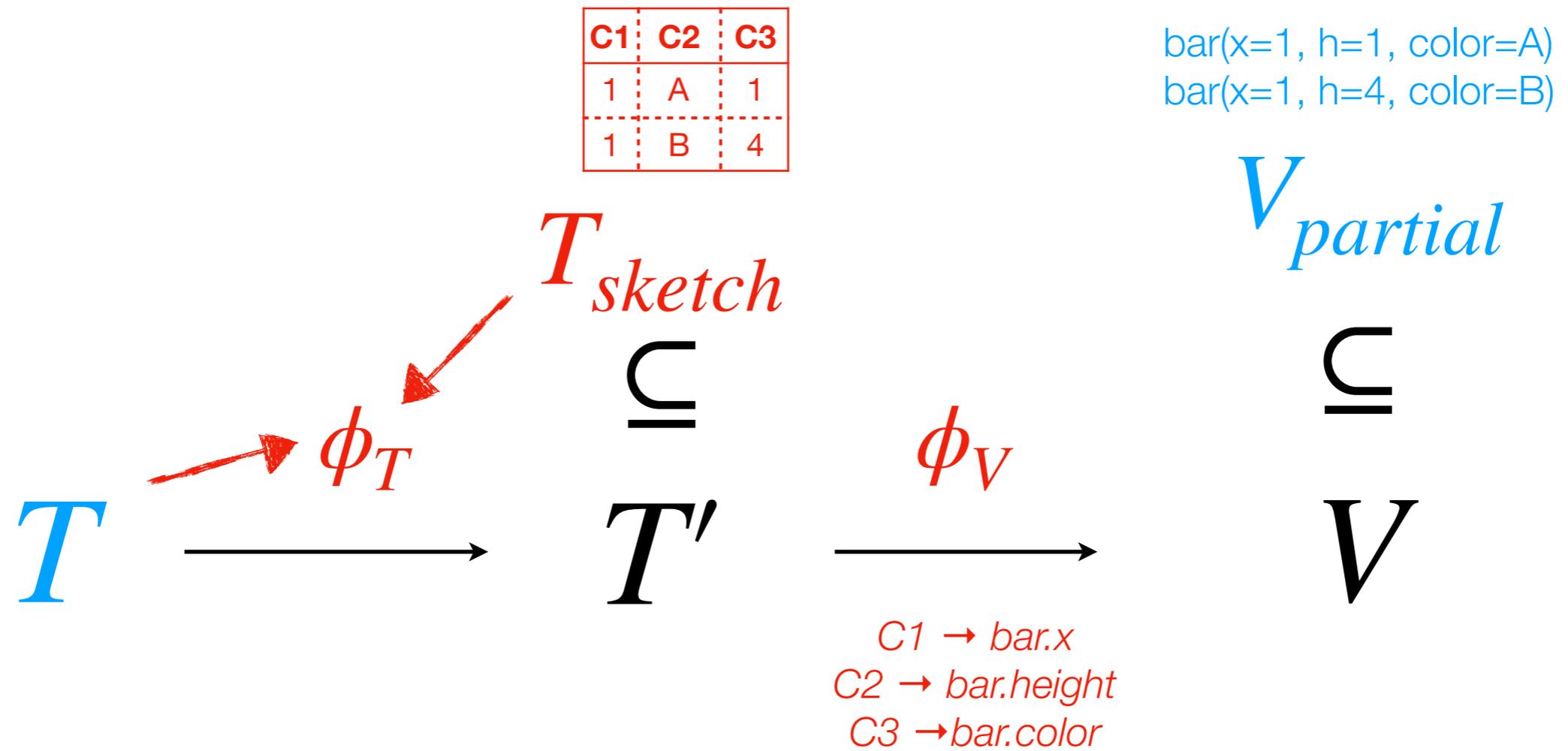
$\phi_V^{-1}$

$T_{sketch}$

C1	C2	C3
1	A	1
1	B	4

Key: formalize visualization as mappings  
 (and leave the challenges for tables)

# Step 2: Data Adapter Synthesis



Requirement:  $\phi_T(T) \supseteq T_{sketch}$

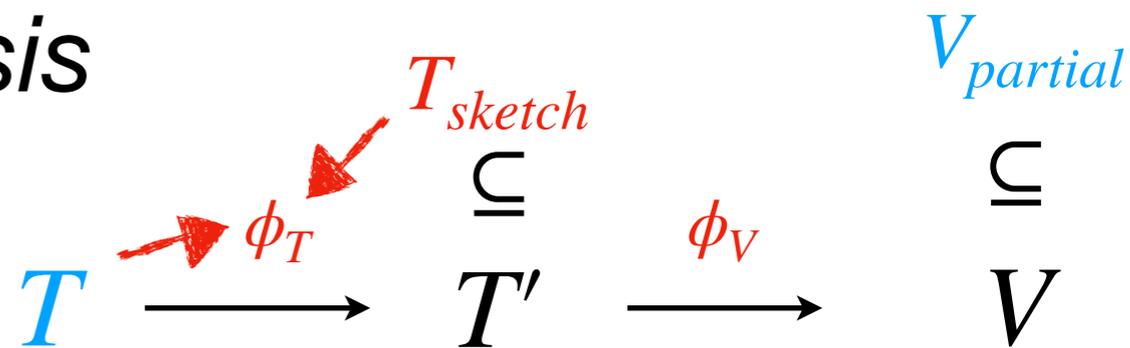
# Step 2: Data Adapter Synthesis

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

X	Key	Val
1	A	1
1	B	4

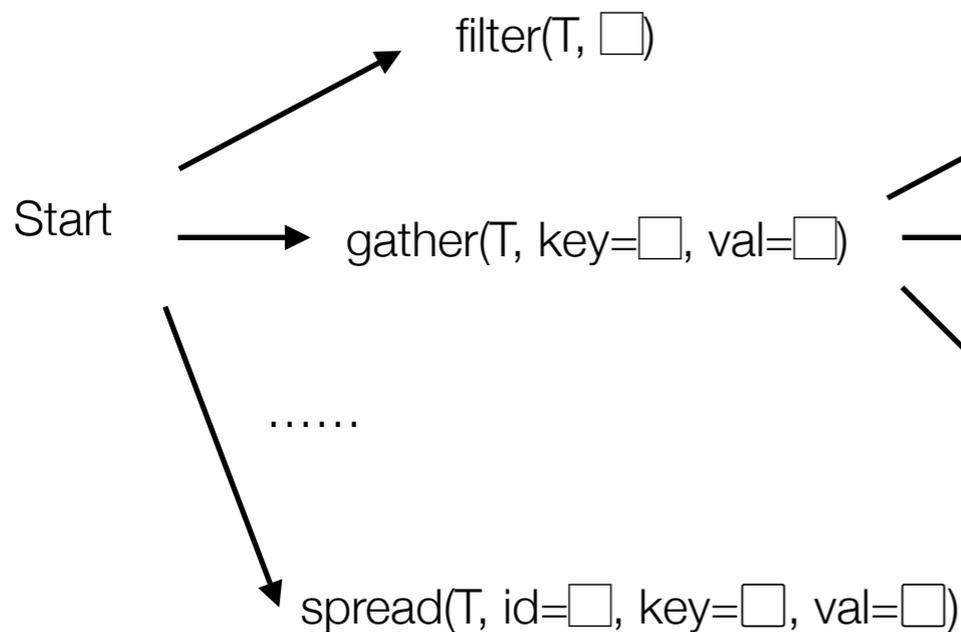
Requirement:  $\phi_T(T) \supseteq T_{sketch}$

Holes "□" are uninstantiated parameters of the partial program



filter(T, A > 0) ❌

filter(T, A == 1) ❌



gather(T, key=C, val=□)

gather(T, key=A, val=□)

gather(T, key=X, val=□)

gather(T, key=X, val=[A, B, C]) ✓

gather(T, key=X, val=[A, B]) ❌

gather(T, key=X, val=[A]) ❌

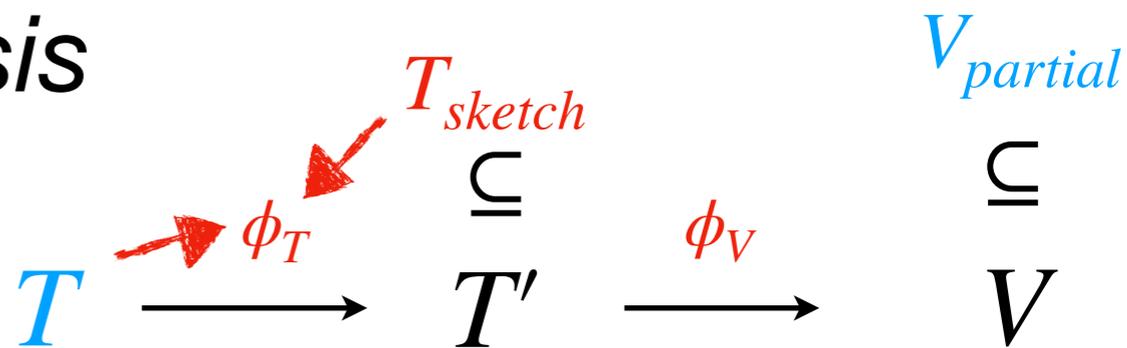
X	Key	Val
1	A	1
1	B	4
1	C	3
2	A	2
...	...	...

# Step 2: Data Adapter Synthesis

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

X	Key	Val
1	A	1
1	B	4

Requirement:  $\phi_T(T) \supseteq T_{sketch}$



For any predicate, we have

$\phi_T(T) \subseteq$

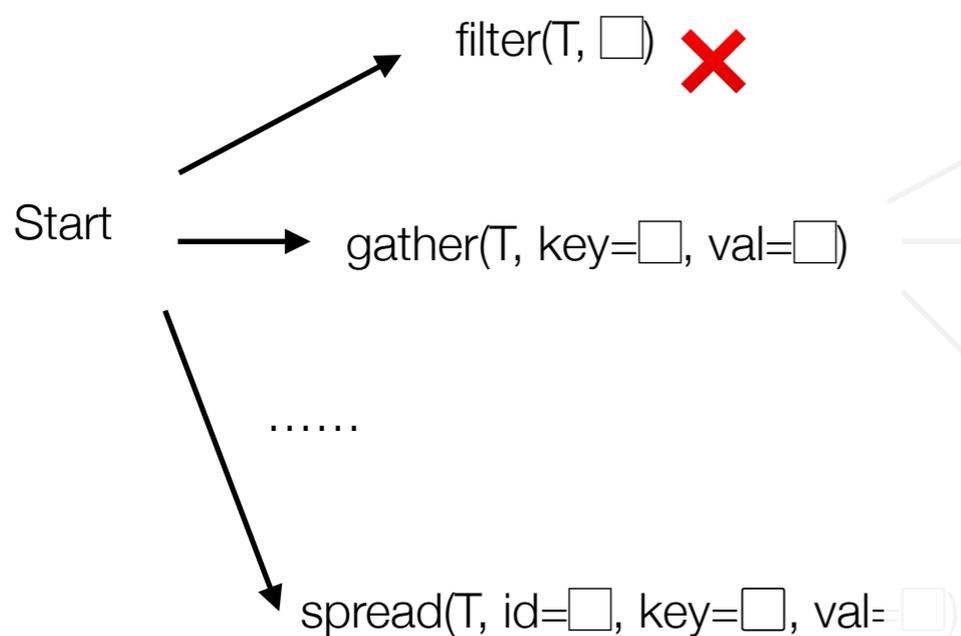
X	A	B	C
1	1	4	2
2	2	3	2
3	5	2	1
4	3	6	1

Contradicts:

1	A	1
1	B	4

$\not\subseteq$

X	A	B	C
1	1	4	2
2	2	3	2
3	5	2	1
4	3	6	1



gather(T, key=C, val=□)

**Forward reasoning**  
 Given  $T$  and partial  $\phi_T$ ,  
 what's the property of the output  $\phi_T(T)$ ?

gather(T, key=X, val=[A])

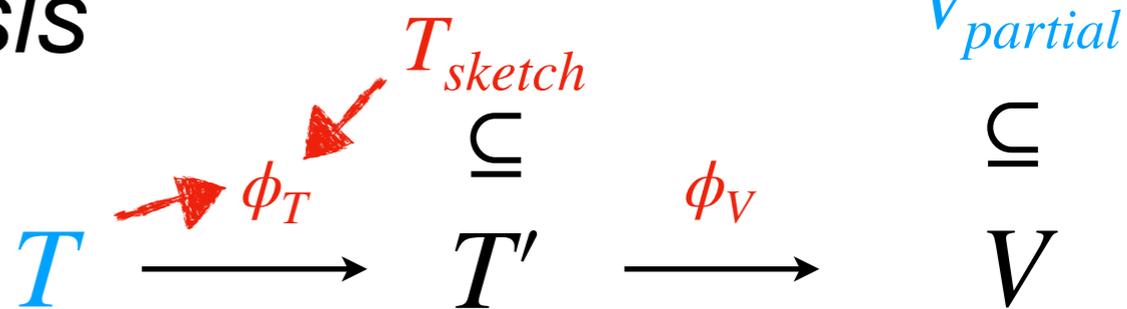
1	1	A
1	4	B
1	3	C
2	2	A
...	...	...

# Step 2: Data Adapter Synthesis

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

X	Key	Val
1	A	1
1	B	4

Requirement:  $\phi_T(T) \supseteq T_{sketch}$



$T_{sketch} =$

c1	c2	c3
1	A	1
1	B	4

Thus, 

C	A	B
1	1	4

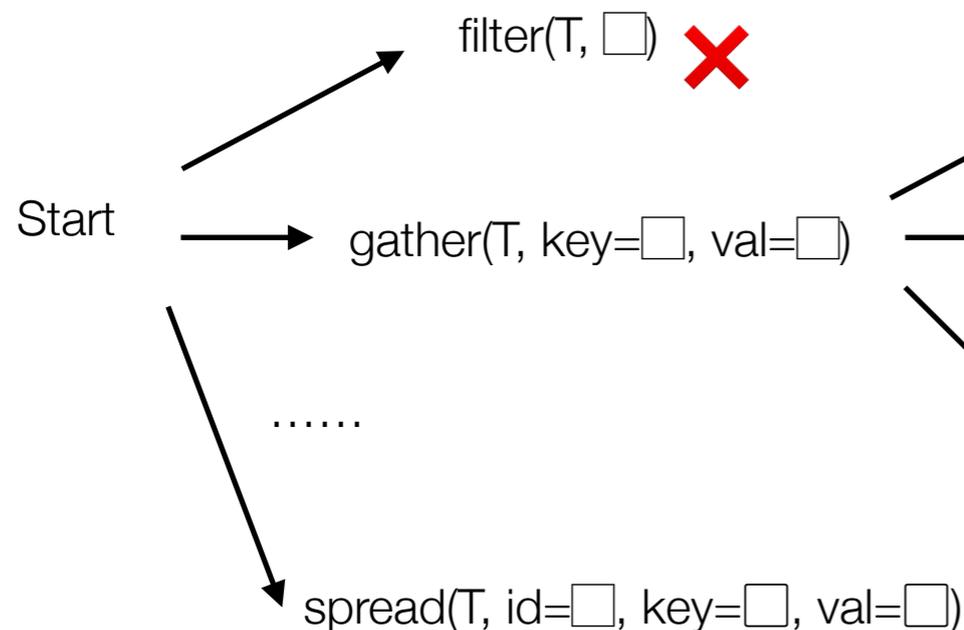
 $\subseteq T_{in}$

Contradicts:

C	A	B
1	1	4

 $\not\subseteq$ 

X	A	B	C
1	1	4	2
2	2	3	2
3	5	2	1
4	3	6	1



gather(T, key=C, val= $\square$ ) ❌

**Backward reasoning:**  
 Given property  $\phi_T(T) \supseteq T_{sketch}$  and partial  $\phi_T$ ,  
 what's the property of  $T$ ?

X	Y	Label
1	1	A
1	4	B
1	3	C
2	2	A
...	...	...

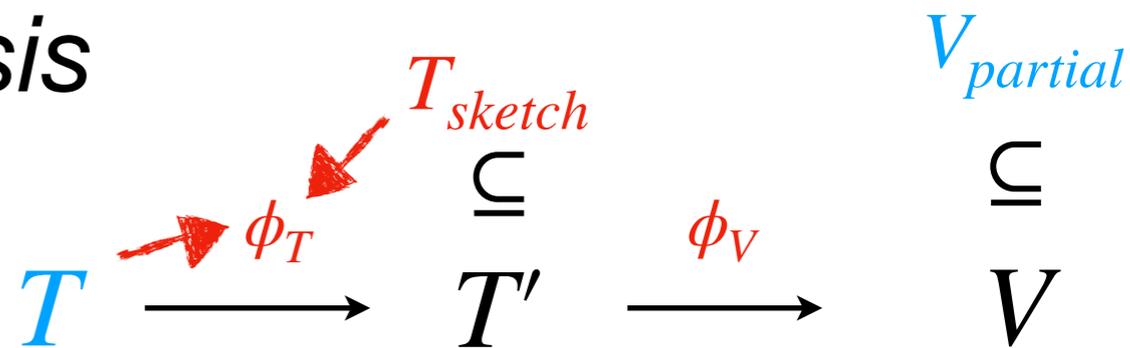
gather(T, key=X, val=[A])

# Step 2: Data Adapter Synthesis

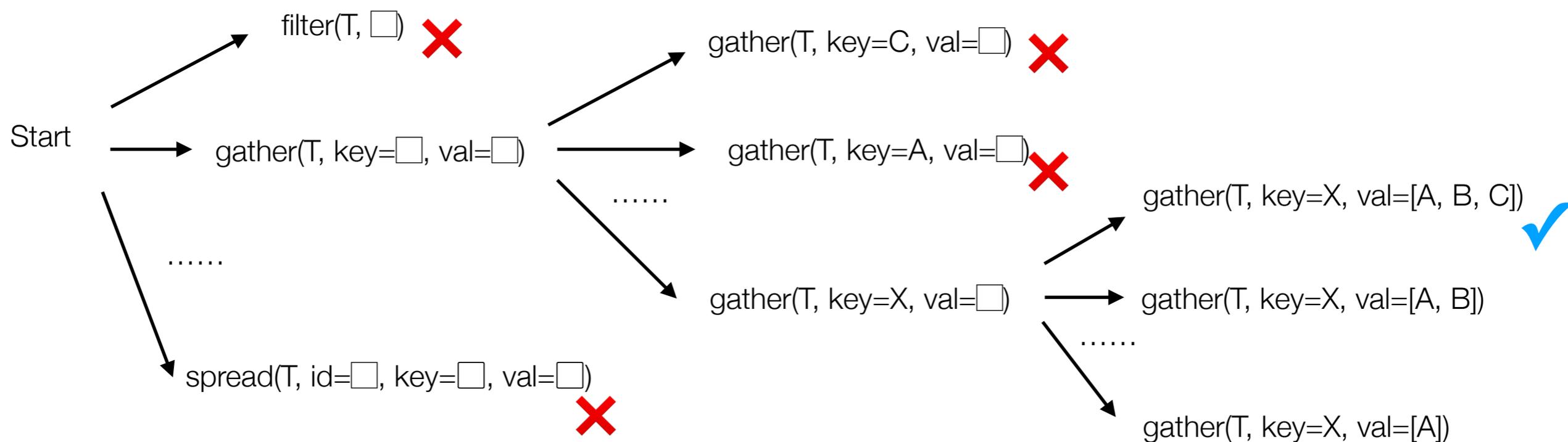
X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

X	Key	Val
1	A	1
1	B	4

Requirement:  $\phi_T(T) \supseteq T_{sketch}$



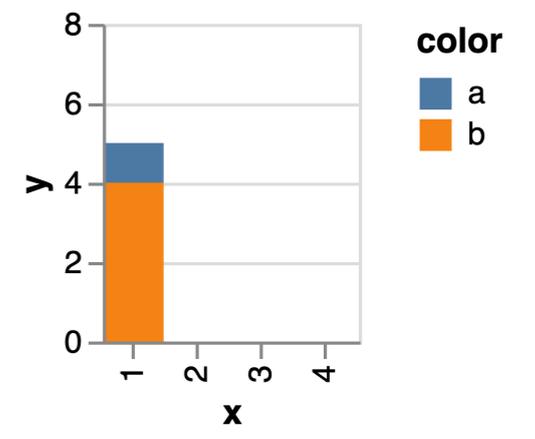
**Contribution: Bidirectional reasoning**  
 Inductively defined for all operators in  $\mathcal{L}_T$



# Visualization by Example

$$\phi_V(\phi_T(T)) \supseteq V_{\text{partial}}$$

Potentially multiple  $(\phi_T, \phi_V)$  pairs can satisfy the specification.

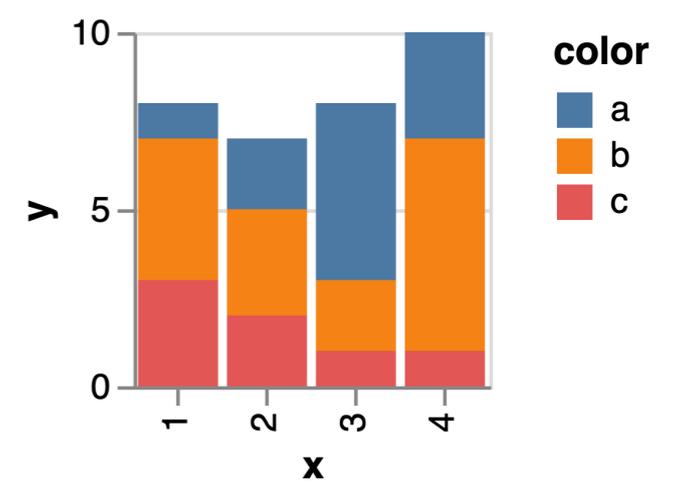


$V_{\text{partial}}$

bar(x=1, h=1, color=A)  
bar(x=1, h=4, color=B)

$\cup$

bar(x=1, h=1, color=A)  
bar(x=1, h=4, color=B)  
bar(x=1, h=3, color=C)  
bar(x=2, h=2, color=A)  
.....



$T$

X	A	B	C
1	1	4	3
2	2	3	2
3	5	2	1
4	3	6	1

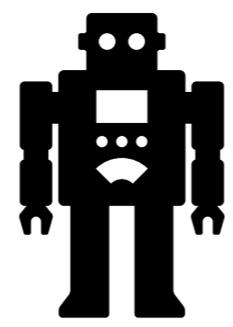
$\phi_T$

gather(  
 $T$ ,  
 $id=X$ ,  
 $key=[A,B,C]$ )

X	Key	Val
1	A	1
1	B	4
1	C	3
2	A	2
...	...	...

$\phi_V$

$X \rightarrow bar.x$   
 $Val \rightarrow bar.height$   
 $Key \rightarrow bar.color$



# Experiment: Viser

## Question 1 (Performance):

Can fast can Viser solve practical visualization problems?

## Question 2 (Usability):

How many geometric objects does the user need to demonstrate?

- **Data Adapter** (R tidyverse library)
  - filter, join, gather, spread, mutate, unite, separate, select
- **Visual Program** (Vega-Lite)
  - Line, Bar, Scatter, Area
  - Stacked charts, Faceted chart, Layered chart
- **83 benchmarks from**
  - Stack Overflow
  - Excel/R tutorials
- **Evaluation**
  - 60
  - Pa
  - fro

Input table size

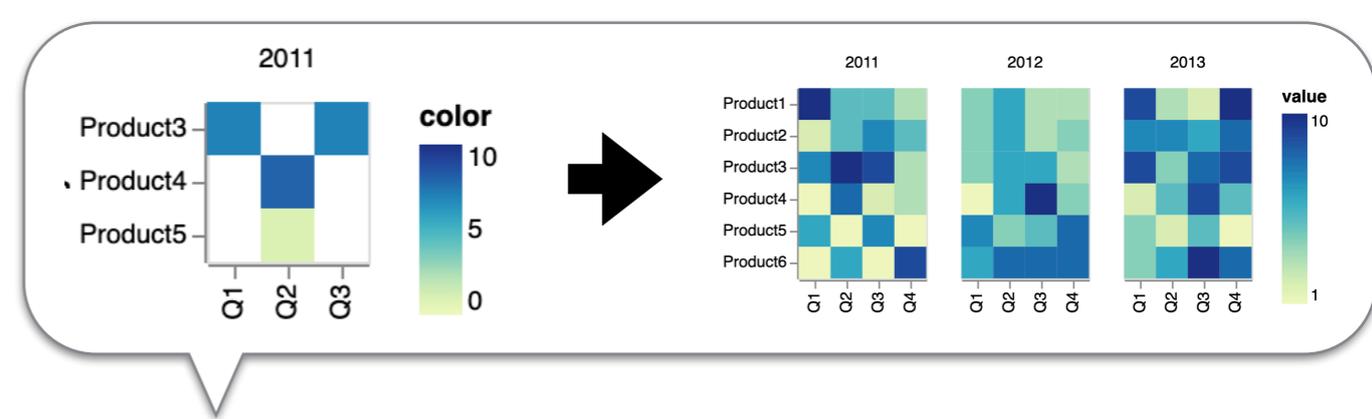
Ranges from **4x3** to **3686x9**,  
average size **100x10**

Program Complexity

1-4 statements,

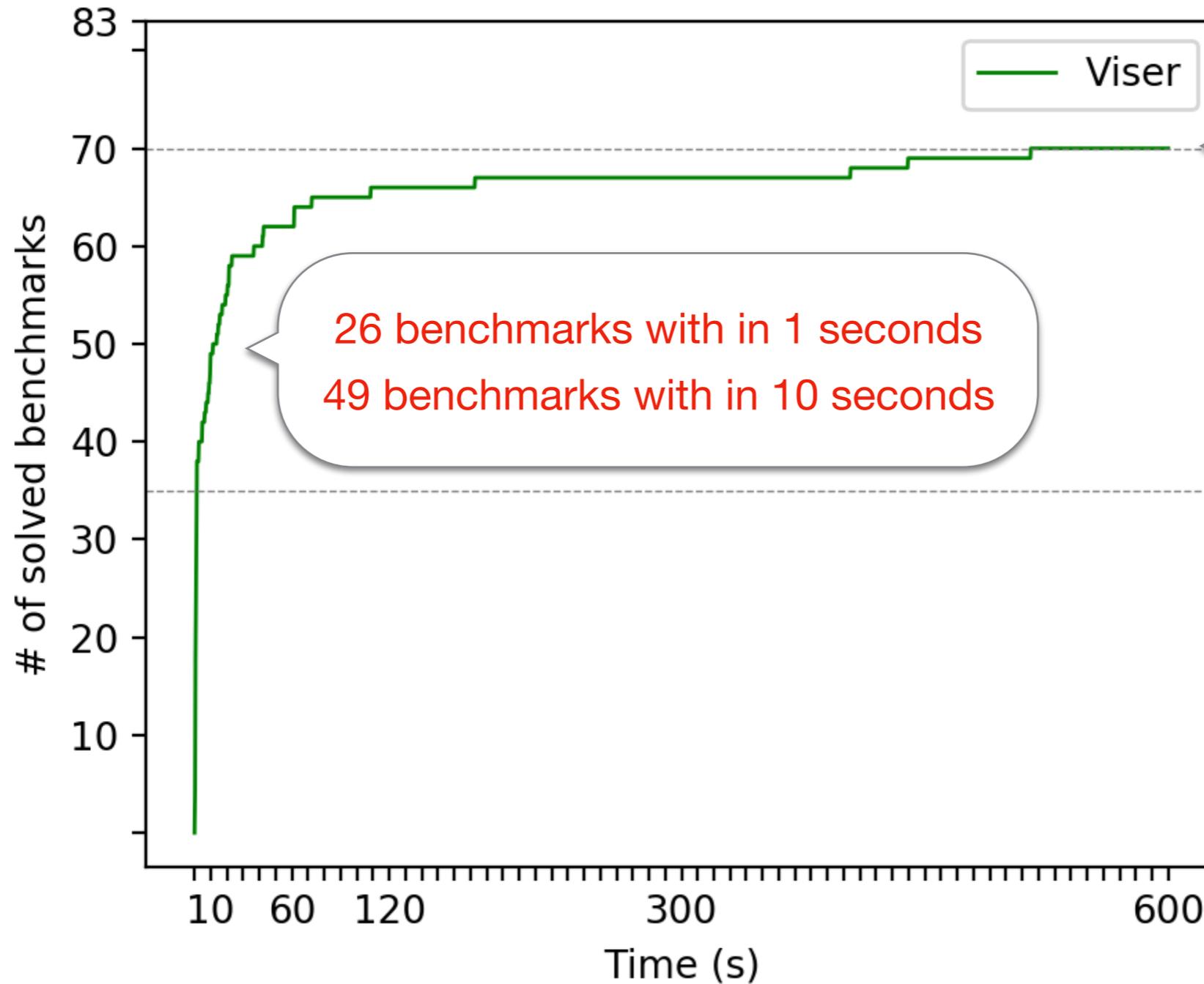
On average 20 decisions to  
make for each program

# Experiment



Partial visualization size = 4

(i.e., 4 random geometric objects from the full visualization)

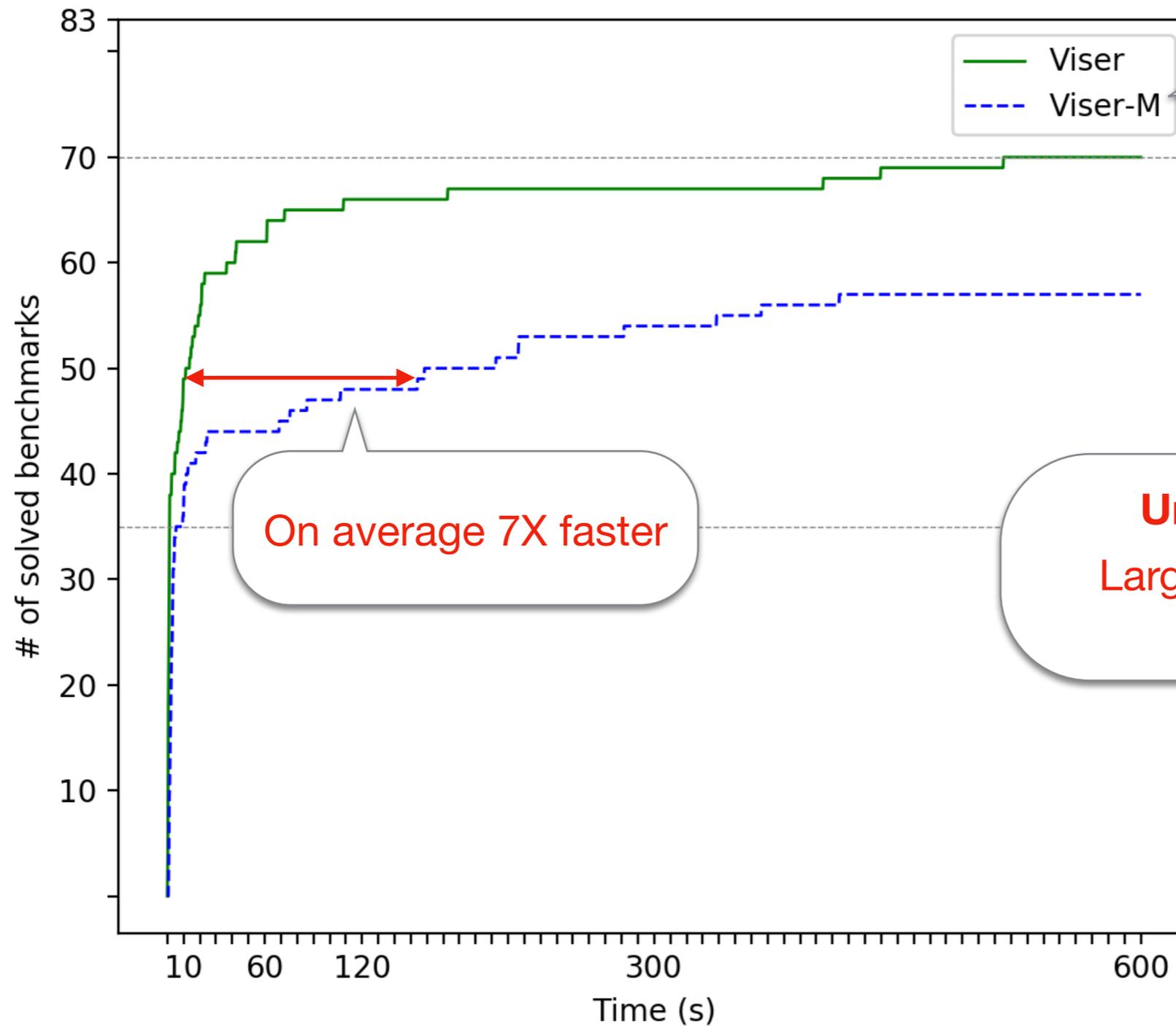


26 benchmarks with in 1 seconds  
49 benchmarks with in 10 seconds

Solves 70 out of 83 benchmarks

# Performance Experiment

Partial visualization size = 4



## Baseline Viser-M

a variation of Viser without bidirectional pruning [Feng PLDI18]

Solves 17 more benchmarks

On average 7X faster

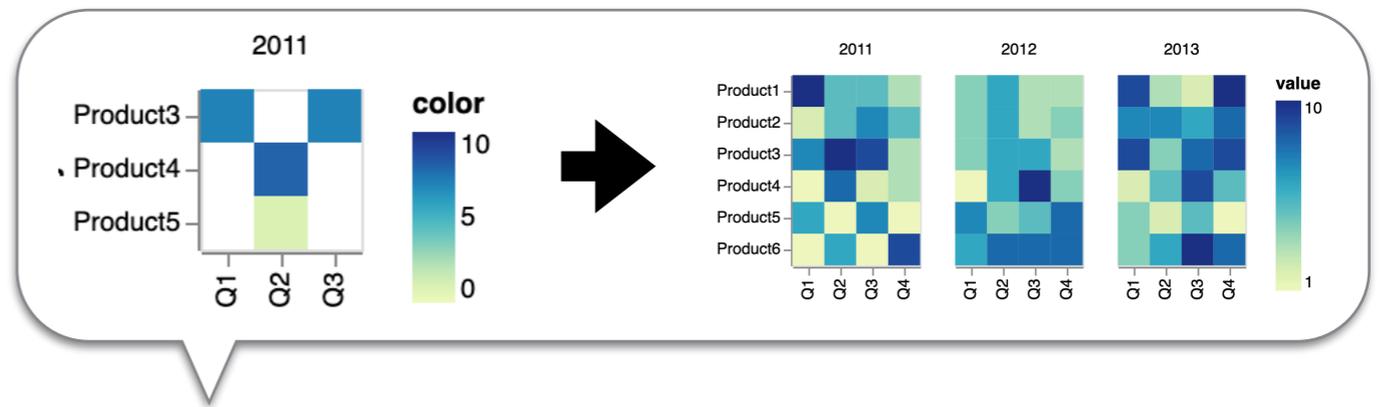
## Unsolved benchmarks

Large input table & complex transformations

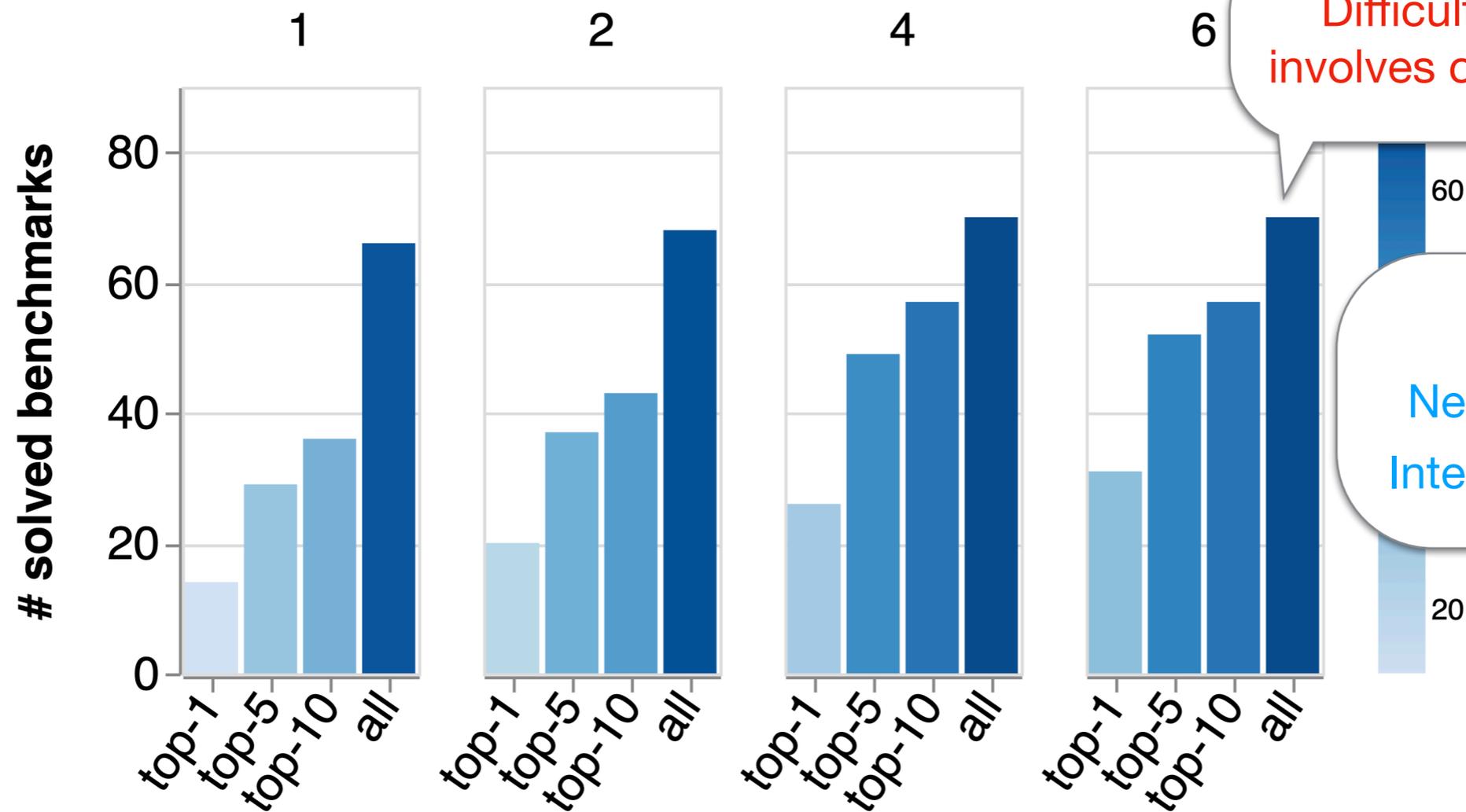
## Look ahead

Multi-modal synthesis

# Usability Experiment



## Partial Visualization Size



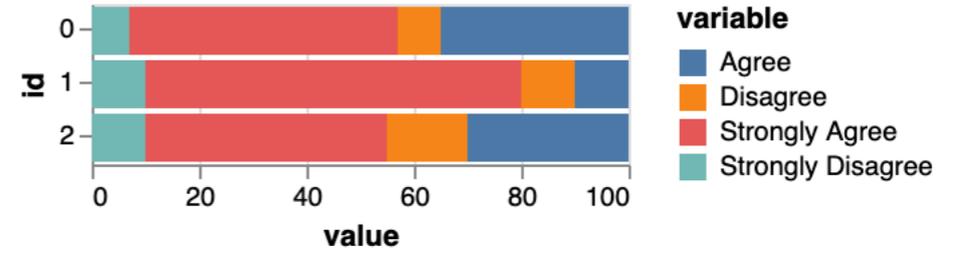
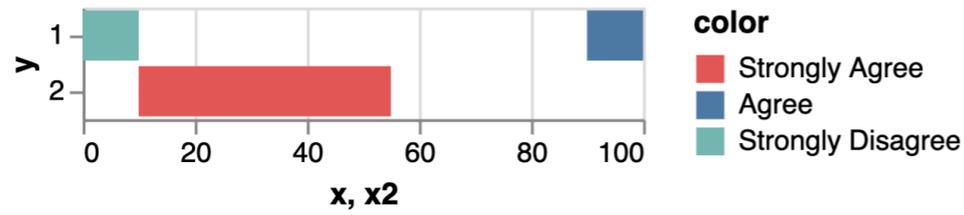
Difficult tasks often involves custom filtering

Look ahead  
Negative examples,  
Interactive refinement

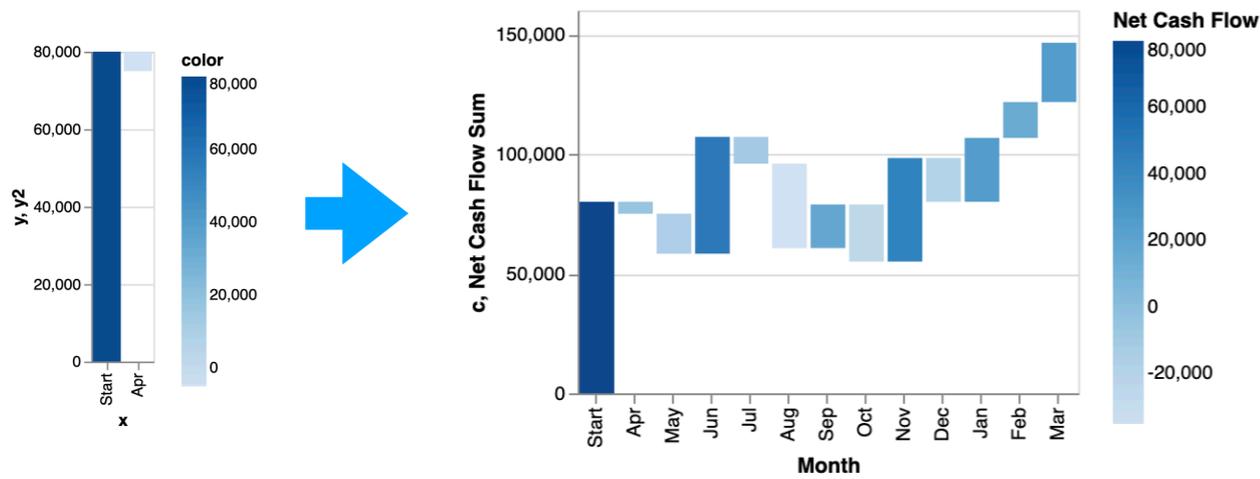
Can solve a lot benchmarks with a small number of examples.

Increasing size of  $V_{partial}$ , makes expected solutions rank higher

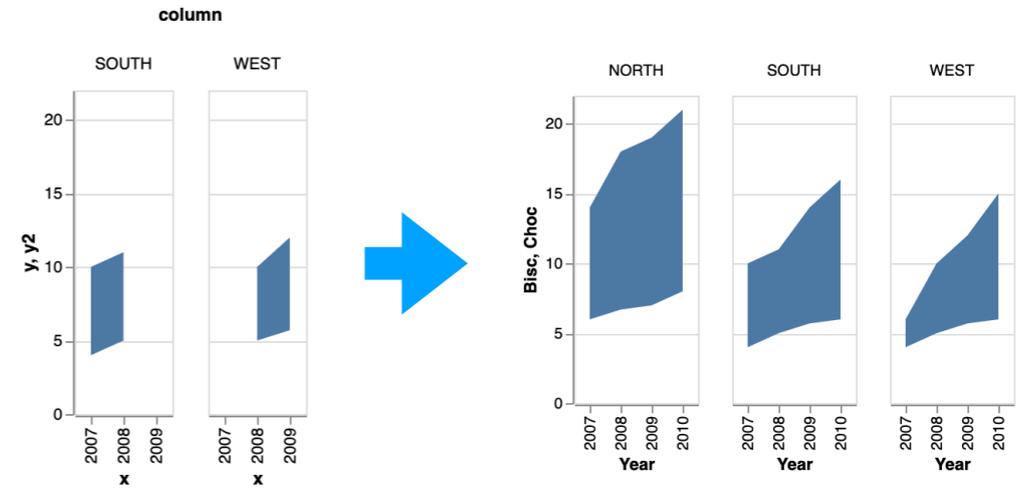
# Visualizations



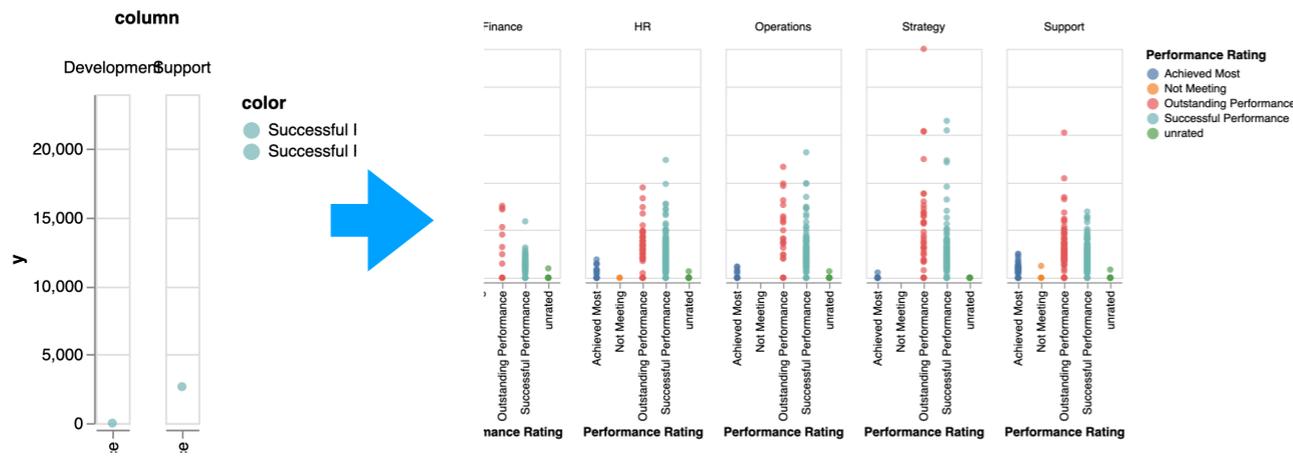
Survey result



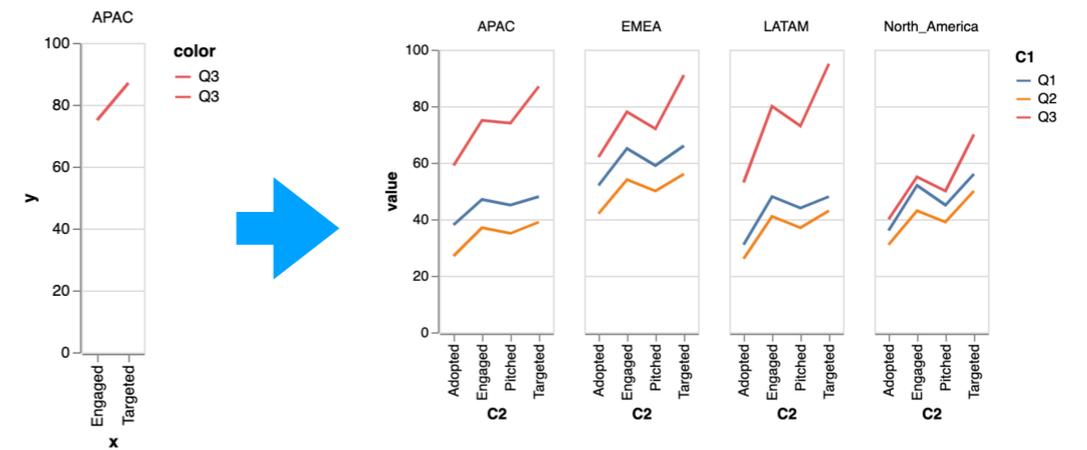
Net cash flow in a year



Housing price in different region

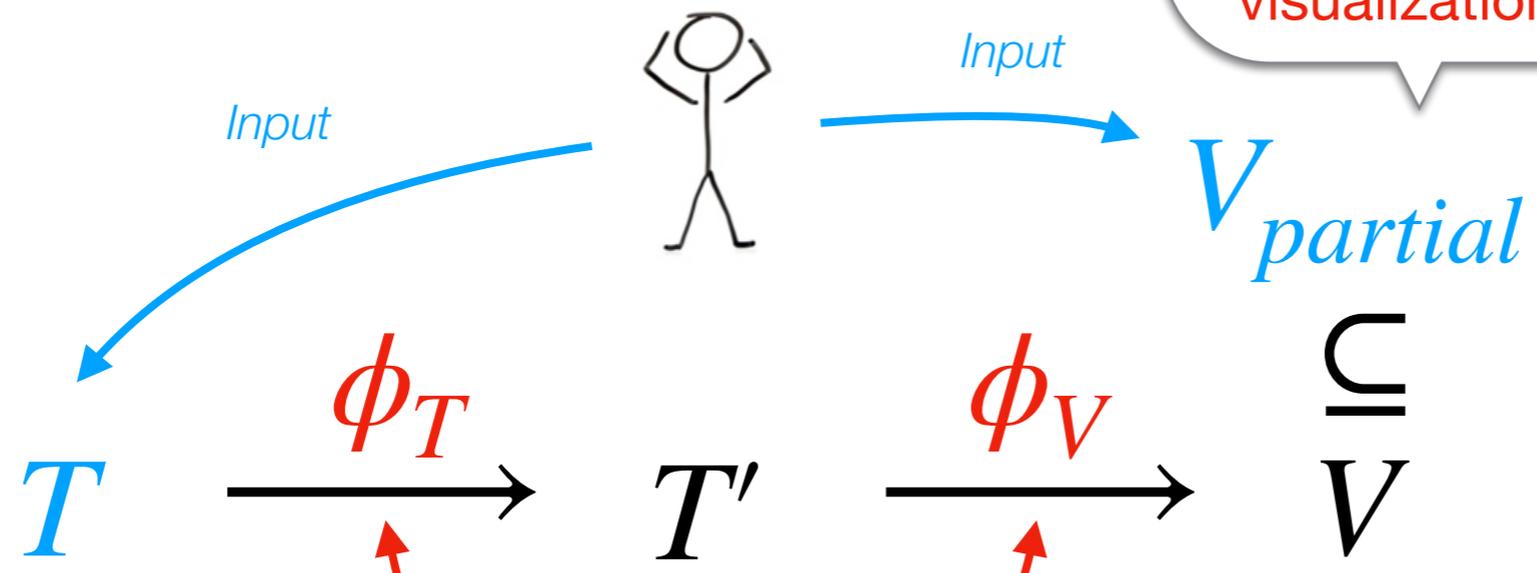


Housing price in different region



Product price in different region

# Visualization by Example



**Contribution 1**  
Define and formalize the visualization synthesis problem

**More questions?**  
Talk to: Chenglong Wang  
[clwang@cs.washington.edu](mailto:clwang@cs.washington.edu)



**Contribution 3**  
Bidirectional analysis for pruning partial programs

**Contribution 2**  
Compositional synthesis of visualizations

Given  $T$ ,  $V_{partial}$ , synthesize  $\phi_T, \phi_V$ , such that  $\phi_V(\phi_T(T)) \supseteq V_{partial}$